## **EXPECTED VALUE of a RV**

corresponds to the *average* value one would get for the RV when repeating the experiment, *independently*, infinitely many times. More accurately, consider a Random Independent Sample (RIS) of *n* values of *X* (e.g. 0, 1, 1, 0, 2, 1, 2, 1, 1, 0) and the corresponding Sample Mean  $\bar{X} \equiv \frac{\sum_{i=1}^{n} X_{i}}{n} \equiv \sum_{A \parallel i} i \times f_{i} \left(= 0 \times \frac{3}{10} + 1 \times \frac{5}{10} + 2 \times \frac{2}{10} = 0.9\right)$ , where  $f_{i}$  are the observed *relative* frequencies (of each possible value). We know that, as *n* (the sample size) increases, each  $f_{i}$  tends to the corresponding  $\Pr(X = i)$ . This implies that, in the same limit,  $\bar{X}$  tends to  $\sum_{A \parallel i} i \cdot \Pr(X = i)$ , which we denote  $\mathbb{E}(X)$  and call the expected (mean) value of *X* (so, in the end, the expected value is computed from the theoretical probabilities, not by doing the experiment). Note that  $\sum_{A \parallel i} i \cdot \Pr(X = i)$  is a 'weighted' average of all possible values of *X* by their probabilities. And, as we have two names for it, we also have two alternate notations,  $\mathbb{E}(X)$  is sometimes denoted  $\mu_{x}$  (the Greek 'mu').

### EXAMPLES:

- When X is the number of dots in a single roll of a die, we get  $\mathbb{E}(X) = \frac{1+2+3+4+5+6}{6} = 3.5$ (for a symmetric distribution, the mean is at the centre of symmetry - for any other distribution, it is at the 'center of mass'). Note that the name 'expected' value is somehow misleading.
- Let Y be the larger of the two numbers when rolling two dice.  $\mathbb{E}(Y) = 1 \times \frac{1}{36} + 2 \times \frac{3}{36} + 3 \times \frac{5}{36} + 4 \times \frac{7}{36} + 5 \times \frac{9}{36} + 6 \times \frac{11}{36} = \frac{1+6+15+28+45+66}{36} = \frac{161}{36} = 4.47\overline{2}.$
- Let U have the following (arbitrarily chosen) distribution:

U =	0	1	2	3	4
Prob:	0.3	0.2	0.4	0	0.1

 $\mathbb{E}(U) = 0.2 + 0.8 + 0.4 = 1.4.$ 

What happens to the expected value of X when we **transform** it, i.e. define a new RV by:  $U \equiv \frac{X}{1+X}$ , or g(X) in general?

The main thing to remember is that, *in general*, the mean does *not* transform accordingly, i.e.  $\mu_u \neq \frac{\mu_x}{1+\mu_x}$ , etc. This is also true for a transformation of X and Y, i.e.  $\mathbb{E}[h(X,Y)] \neq h(\mu_x, \mu_y)$ .

But (at least one good news), to find the expected value of g(X), h(X, Y), ..., we can bypass constructing the new distribution (which was a tedious process) and use:

$$\begin{split} \mathbb{E}[g(X)] &= \sum_{\text{All } i} g(i) \times \Pr(X=i) \\ \mathbb{E}[h(X,Y)] &= \sum_{\text{All } i,j} h(i,j) \times \Pr(X=i \cap Y=j) \end{split}$$

EXAMPLE:

Based on U, we define  $W = |U-2|^3$  and compute  $\mathbb{E}(U) = 8 \times 0.3 + 1 \times 0.2 + 0 \times 0.4 + 8 \times 0.1 = 3.4$ . Clearly, it would have been a mistake to use  $|1.4 - 2|^3 = 0.216$  (totally wrong).

We can also get the correct answer the 'long' way (just to verify the 'short' answer), by first finding the distribution of W:

W =	8	1	0	8
U =	0	1	2	4
Prob:	0.3	0.2	0.4	0.1

## Exception: Linear Transformations

Only for these, we can find the mean of the new RV by simply replacing X by  $\mu_x$ , thus:

$$\mathbb{E}(a \cdot X + c) = a \cdot \mu_x + c$$

Proof: 
$$\mathbb{E}(a \cdot X + c) = \sum_{\text{All } i} (a \cdot i + c) f_x(i) = a \sum_{\text{All } i} i \times f_x(i) + c \sum_{\text{All } i} f_x(i) = a \cdot \mu_x + c \blacksquare$$
  
EXAMPLE:  $\mathbb{E}(2U - 3) = 2 \times 1.4 - 3 = -0.2$ 

#### Expected values related to a bivariate distribution

When a bivariate distribution is given, the easiest way to compute the *individual* expected values (of X and Y) is through the marginals.

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EXAMPLE:

$$A = 1 \quad 2 \quad 3$$

$$Y = 0 \quad 0.1 \quad 0 \quad 0.3 \quad 0.4$$

$$1 \quad 0.3 \quad 0.1 \quad 0.2 \quad 0.6$$

$$0.4 \quad 0.1 \quad 0.5$$

we compute  $\mathbb{E}(X) = 1 \times 0.4 + 2 \times 0.1 + 3 \times 0.5 = 2.1$  and  $\mathbb{E}(Y) = 0 \times 0.4 + 1 \times 0.6 = 0.6$ .

This is how we also deal with an expected value of  $g_1(X)$  and/or  $g_2(Y)$ .

Only when the new variable is defined by h(X, Y), we have 'weigh-average' the whole table. For example:  $\mathbb{E}(X \cdot Y) = 1 \times 0 \times 0.1 + 2 \times 0 \times 0 + 3 \times 0 \times 0.3 + 1 \times 1 \times 0.3 + 2 \times 1 \times 0.1 + 3 \times 1 \times 0.2 = 1.1$ 

More EXAMPLES:

- $\mathbb{E}[(X-1)^2] = 0^2 \times 0.4 + 1^2 \times 0.1 + 2^2 \times 0.5 = 2.1$
- $\mathbb{E}\left[\frac{1}{1+Y^2}\right] = \frac{1}{1+0^2} \times 0.4 + \frac{1}{1+1^2} \times 0.6 = 0.7$
- $\mathbb{E}\left[\frac{(X-1)^2}{1+Y^2}\right]$  (multiplying the last two results would be *wrong*). Here it may help to first build the corresponding table of the  $\frac{(X-1)^2}{1+Y^2}$  values:  $\boxed{\begin{array}{c|c} 0 & 1 & 4 \\ \hline 0 & \frac{1}{2} & 2 \end{array}}$ . Answer: 1.2 + 0.05 + 0.4 = 1.65

For Linear Transformation (of *two* RVs) we get:

$$\mathbb{E}(a \cdot X + b \cdot Y + c) = a \cdot \mu_x + b \cdot \mu_y + c$$

**Proof:**  $\mathbb{E}(aX+bY+c) = \sum_{i} \sum_{j} (a \times i + b \times j + c) f_{xy}(i,j) = a \sum_{i} i \times f_x(i) + b \sum_{j} j \times f_y(j) + c = a \cdot \mathbb{E}(X) + b \cdot \mathbb{E}(Y) + c$  Note that X and Y need not be independent!

EXAMPLE: Using the previous bivariate distribution,  $\mathbb{E}(2X - 3Y + 4)$  is simply  $2 \times 2.1 - 3 \times 0.6 + 4 = 6.4$ 

The previous formula easily extends to *any number* of RVs (again, not necessarily independent!)

$$\mathbb{E}(a_1X_1 + a_2X_2 + \dots + a_kX_k + c) =$$
$$a_1\mathbb{E}(X_1) + a_2\mathbb{E}(X_2) + \dots + a_k\mathbb{E}(X_k) + c$$

Can **Independence** help (in other cases of expected value)?

Yes, the expected value of a *product* of RVs equals the product of the individual expected values, but ONLY when these RVs are *independent*:

$$\mathbb{E}(X \cdot Y) = \mathbb{E}(X) \cdot \mathbb{E}(Y)$$

Proof:

$$\mathbb{E}(X \cdot Y) = \sum_{i} \sum_{j} i \times j \times f_x(i) \times f_y(j) = \left(\sum_{i} i \times f_x(i)\right) \times \left(\sum_{j} j \times f_y(j)\right) = \mathbb{E}(X) \cdot \mathbb{E}(Y) \blacksquare$$

The statement can actually be made more **general**: When X and Y are *independent* 

$$\mathbb{E}\left[g_1(X) \cdot g_2(Y)\right] = \mathbb{E}\left[g_1(X)\right] \cdot \mathbb{E}\left[g_2(Y)\right]$$

## Moments of a RV

There are two types of 'moments', Simple Moments

 $\mathbb{E}(X^k)$ 

and Central Moments

$$\mathbb{E}\left[(X-\mu_x)^k\right]$$

where k is an integer.

**Special cases:** The 0<sup>th</sup> moment is identically equal to 1. The first simple moment is  $\mu_x$  (yet another name for it!). The second simple moment is  $\mathbb{E}(X^2) \neq \mu_x^2$ , etc. The first central moment is identically equal to 0. The second central moment  $\mathbb{E}[(X - \mu_x)^2]$  must be  $\geq 0$  (averaging non-negative quantities cannot result in a negative number). It is of such importance that it gets its own name: the **variance** of X, denoted Var(X). When doing the computation 'by hand', it helps to realize that  $\mathbb{E}[(X - \mu_x)^2] = \mathbb{E}(X^2) - \mu_x^2$ .

As a measure of the *spread* of the distribution of X values, we take  $\sigma_x \equiv \sqrt{\operatorname{Var}(X)}$ and call it the standard deviation of X. For all distributions, the  $(\mu - \sigma, \rho + \sigma)$  interval should contain the 'bulk' of the distribution, i.e. anywhere from 50 to 90% (in terms of the corresponding histogram).

Finally, **skewness** is defined as  $\frac{\mathbb{E}\left[(X-\mu_x)^3\right]}{\sigma_x^3}$  (it measures to what extent is the distribution non-symmetric, or 'skewed'), and **kurtosis** as  $\frac{\mathbb{E}\left[(X-\mu_x)^4\right]}{\sigma_x^4}$  (it measures the degree of 'flatness', 3 being its typical value, higher for 'peaked', smaller for 'flat' distributions). These are a lot less important than the mean and variance (later, we will understand why).

## EXAMPLES:

• X is the number of dots when rolling one die:  $\mu_x = \frac{7}{2}$ ,  $Var(X) = \frac{1^2 + 2^2 + 3^2 + 4^2 + 5^2 + 6^2}{6} - (\frac{7}{2})^2 = \frac{35}{12}$  implying  $\sigma_x = \sqrt{\frac{35}{12}} = 1.7078$ . Note that  $3.5 \pm 1.708$  contains 66.7% of the distribution. Skewness, for a symmetric distribution, is always equal to 0, kurtosis can be

computed from 
$$\mathbb{E}\left[(X-\mu)^4\right] = \frac{(-2.5)^4 + (-1.5)^4 + (-0.5)^4 + 0.5^4 + 1.5^4 + 2.5^4}{6} = 14.729 \Rightarrow \text{kurtosis}$$
  

$$= \frac{14.729}{(\frac{35}{12})^2} = 1.7314 \text{ ('flat')}.$$
• For  $\boxed{U = 0 \ 1 \ 2 \ 4}_{\text{Prob:} \ 0.3 \ 0.2 \ 0.4 \ 0.1} \mu_u = 1.4, \text{Var}(U) = 0^2 \times 0.3 + 1^2 \times 0.2 + 2^2 \times 0.4 + 4^2 \times 0.1 - 1.4^2 = 1.44 \Rightarrow \sigma_u = \sqrt{1.44} = 1.2. \text{ From } \mathbb{E}\left[(U - \mu_u)^3\right] = (-1.4)^3 \times 0.3 + (-0.4)^3 \times 0.2 + 0.6^3 \times 0.4 + 2.6^3 \times 0.1 = 1.008, \text{ the skewness is } \frac{1.008}{1.2^3} = 0.58\overline{3} \text{ (long right tail)},$ 
and from  $\mathbb{E}\left[(U - \mu_u)^4\right] = (-1.4)^4 \times 0.3 + (-0.4)^4 \times 0.2 + 0.6^4 \times 0.4 + 2.6^4 \times 0.1 = 5.7792$ 
the kurtosis equals  $\frac{5.7792}{1.2^4} = 2.787$ 

When X is transformed to Y = g(X), we already know that there is no general 'shortcut' for computing  $\mathbb{E}(Y)$ . This (even more so) applies to the *variance* of Y, which also needs to be computed 'from scratch'. But, we did manage to simplify the expected value of a **linear transformation** of X (i.e., of Y = aX + c). Is there any direct conversion of Var(X) into Var(Y) in this (linear) case?

The answer is 'yes', and we can easily derive the corresponding formula:  $\operatorname{Var}(aX + c) = \mathbb{E}\left[(aX + c)^2\right] - (a\mu_x + c)^2 = \mathbb{E}\left[a^2X^2 + 2acX + c^2\right] - (a\mu_x + c)^2 = a^2\mathbb{E}(X^2) - a^2\mu_x^2 = a^2\operatorname{Var}(X).$ This implies that

$$\sigma_{aX+c} = |a| \cdot \sigma_X$$

#### Moments - the bivariate case

Firstly, there will be the individual moments of X (and, separately, Y), which can be established based on the corresponding *marginal* distribution.

Are there any other (joint) moments? Yes, and again we have the *simple* moments  $\mathbb{E}(X^k \cdot Y^m)$  and the *central* moments  $\mathbb{E}\left[(X - \mu_x)^k \cdot (Y - \mu_y)^m\right]$ . The most important of

these is the *first, first central* moment called the **covariance** of X and Y:

$$\operatorname{Cov}(X,Y) = \mathbb{E}\left[ (X - \mu_x) \cdot (Y - \mu_y) \right] \equiv \mathbb{E}(X \cdot Y) - \mu_x \cdot \mu_y$$

It is obviously 'symmetric', i.e. Cov(X, Y) = Cov(Y, X) and it becomes zero when X and Y are *independent* (but not necessarily the other way round).

Based on Cov(X, Y), one can define the Correlation Coefficient between X and Y by:

$$\rho_{xy} = \frac{\operatorname{Cov}(X, Y)}{\sigma_x \cdot \sigma_y}$$

(Greek letter 'rho'). Its value must be always between -1 and 1.

**Proof:** Obviously,

$$\operatorname{Var}(X - bY) = \operatorname{Var}(X) - 2b\operatorname{Cov}(X, Y) + b^{2}\operatorname{Var}(Y) \ge 0$$

for any value of b, including

$$b = \frac{\operatorname{Cov}(X,Y)}{\operatorname{Var}(Y)}$$

This implies that

$$\operatorname{Var}(X) - 2\frac{\operatorname{Cov}(X,Y)}{\operatorname{Var}(Y)}\operatorname{Cov}(X,Y) + \frac{\operatorname{Cov}(X,Y)^2}{\operatorname{Var}(Y)^2}\operatorname{Var}(Y)$$
$$= \operatorname{Var}(X) - \frac{\operatorname{Cov}(X,Y)^2}{\operatorname{Var}(Y)} \ge 0$$

which, after dividing by Var(X) yields

 $1\geq \rho^2$ 

1 23 EXAMPLE: For one of our previous distributions Y =0 0.10 0.3 0.4 we 0.30.10.2 1 0.60.40.1 0.5 get  $\mu_x = 2.1, \, \mu_y = 0.6, \, \operatorname{Var}(X) = 5.3 - 2.1^2 = 0.89, \, \operatorname{Var}(Y) = 0.6 - 0.6^2 = 0.24, \, \operatorname{Cov}(X, Y) = 0.6 - 0$  $0.3 + 0.2 + 0.6 - 2.1 \times 0.6 = -0.16$  (may be negative), and  $\rho_{xy} = \frac{-0.16}{\sqrt{0.89 \times 0.24}} = -0.3462$ One can also show that  $\rho_{aX+c,bY+d} = \frac{\operatorname{Cov}(aX+c,bY+d)}{\sigma_{aX+c}\cdot\sigma_{bY+d}} = \frac{a\cdot b\cdot\operatorname{Cov}(X,Y)}{|a|\cdot|b|\cdot\sigma_X\cdot\sigma_Y} = \pm \rho_{xy}$  (linear trans-

X =

formation does not change the value of  $\rho$ , but it may change its sign - can you tell when?).

## Linear Combination of RVs

Starting with X and Y, let's see whether we can simplify the expression for  $\operatorname{Var}(aX + bY + c) = \mathbb{E}\left[(aX + bY + c)^2\right] - \left(a\mu_x + b\mu_y + c\right)^2 = a^2\mathbb{E}(X^2) + b^2\mathbb{E}(Y^2) + 2ab\mathbb{E}(X \cdot Y) - a^2\mu_x^2 - b^2\mu_x^2 - 2ab\mu_x\mu_y =$ 

$$a^{2}$$
Var $(X) + b^{2}$ Var $(Y) + 2ab$ Cov $(X, Y)$ 

Independence eliminates the last term.

This result can be easily **extended** to a linear combination of *any number* of random variables:

$$Var(a_1X_1 + a_2X_2 + ...a_kX_k + c) =$$

$$a_1^2Var(X_1) + a_2^2Var(X_2) + .... + a_k^2Var(X_k) +$$

$$2a_1a_2Cov(X_1, X_2) + 2a_1a_3Cov(X_1, X_3) + ...$$

$$... + 2a_{k-1}a_kCov(X_{k-1}, X_k)$$

Mutual *independence* (if present) eliminates the last row of  $\binom{k}{2}$  covariances.

And finally a formula for a covariance of one *linear combination* of RVs against another:

$$Cov (a_1X_1 + a_2X_2 + ..., b_1Y_1 + b_2Y_2 + ...) =$$
  

$$a_1b_1Cov(X_1, Y_1) + a_1b_2Cov(X_1, Y_2)$$
  

$$+a_2b_1Cov(X_2, Y_1) + a_2b_2Cov(X_2, Y_2) + ...$$

(I will call this the *distributive law* of covariance).

# Sample Mean and its distribution

Consider a random independent sample of size n from an arbitrary distribution. We know that the sample mean

$$\bar{X} = \frac{\sum_{i=1}^{n} X_i}{n}$$

is itself a RV with its own distribution. Regardless how that distribution looks like, its expected value must be the same as the expected value of the distribution from which we sample. Proof:  $\mathbb{E}(\bar{X}) = \frac{1}{n}\mathbb{E}(X_1) + \frac{1}{n}\mathbb{E}(X_2) + \dots + \frac{1}{n}\mathbb{E}(X_n) = \frac{1}{n}\mu + \frac{1}{n}\mu + \dots + \frac{1}{n}\mu = \mu$ 

That's why  $\bar{X}$  is often used as an estimator of  $\mu$ , when its value is unknown.

Similarly,  $\operatorname{Var}(\bar{X}) = (\frac{1}{n})^2 \operatorname{Var}(X_1) + (\frac{1}{n})^2 \operatorname{Var}(X_2) + \dots + (\frac{1}{n})^2 \operatorname{Var}(X_n) = (\frac{1}{n})^2 \sigma^2 + (\frac{1}{n})^2 \sigma^2 + \dots + (\frac{1}{n})^2 \sigma^2 = \frac{\sigma^2}{n}$  where  $\sigma$  is the standard deviation of the original distribution. This implies that

$$\sigma_{\bar{X}} = \frac{\sigma}{\sqrt{n}}$$

The standard deviation of  $\overline{X}$  (sometimes called the standard error of  $\overline{X}$ ) is  $\sqrt{n}$  times smaller than that of the original distribution. Note that the standard error tends to zero as sample size increases.

Now, how about the *shape* of the  $\bar{X}$ -distribution, how does it relate to the shape of the sampled distribution? The surprising answer is: it doesn't. For *n* bigger than say 5, the

distribution of  $\bar{X}$  quickly approaches the *same* regular shape, regardless of how the original distribution looked like.

Now, consider a random independent sample of size n from a bi-variate distribution, where  $(X_1, Y_1), (X_2, Y_2), ..., (X_n, Y_n)$  are the individual *pairs* of observations. Then,  $\operatorname{Var}(X_1 + X_2 + ..., + X_n) = \operatorname{Var}(X_1) + \operatorname{Var}(X_2) + ... + \operatorname{Var}(X_n) \equiv n \operatorname{Var}(X)$  and, similarly,  $\operatorname{Var}(\sum_{i=1}^n Y_i) = n \operatorname{Var}(Y)$ . Similarly,  $\operatorname{Cov}(\sum_{i=1}^n X_i, \sum_{i=1}^n Y_i) = \operatorname{Cov}(X_1, Y_1) + \operatorname{Cov}(X_2, Y_2) + ... + \operatorname{Cov}(X_n, Y_n) = n \operatorname{Cov}(X, Y)$ . All this implies that the correlation coefficient between  $\sum_{i=1}^n X_i$  and  $\sum_{i=1}^n Y_i$  equals  $\frac{n \operatorname{Cov}(X,Y)}{\sqrt{n \operatorname{Var}(X)} \cdot \sqrt{n \operatorname{Var}(Y)}} \equiv \rho_{xy}$  (the correlation between a single X and Y pair). The same is true for the corresponding sample means  $\bar{X} \equiv \frac{\sum_{i=1}^n X_i}{n}$  and  $\bar{Y} \equiv \frac{\sum_{i=1}^n Y_i}{n}$ , why?

## Conditional expected value

is, simply put, an expected value computed using the corresponding *conditional* distribution, e.g.

$$\mathbb{E}(X|Y=1) = \sum_{i} i \times f_x(i \mid Y=1)$$

etc.

EXAMPLE: Using our old bivariate distributions

$$Y = \begin{array}{ccccccc} 1 & 2 & 3 \\ \hline 0.1 & 0 & 0.3 \\ 1 & 0.3 & 0.1 & 0.2 \\ 0.4 & 0.1 & 0.5 \end{array} 0.6$$

 $\mathbb{E}(X|Y =$ 

X =

1) is constructed based on the corresponding conditional distribution

$$X|Y=1$$
 1
 2
 3

 Prob:
  $\frac{3}{6}$ 
 $\frac{1}{6}$ 
 $\frac{2}{6}$ 

by the usual process:  $1 \cdot \frac{3}{6} + 2 \cdot \frac{1}{6} + 3 \cdot \frac{2}{6} = 1.8\overline{3}$  (note that this is different from  $\mathbb{E}(X) = 2.1$  calculated previously). Similarly  $\mathbb{E}(X^2|Y=1) = 1^2 \cdot \frac{3}{6} + 2^2 \cdot \frac{1}{6} + 3^2 \cdot \frac{2}{6} = 4.1\overline{6}$ . These imply that  $\operatorname{Var}(X|Y=1) = 4.1\overline{6} - 1.8\overline{3}^2 = 0.8056$ . Also,  $\mathbb{E}(\frac{1}{X}|Y=1) = \frac{1}{1} \cdot \frac{3}{6} + \frac{1}{2} \cdot \frac{1}{6} + \frac{1}{3} \cdot \frac{2}{6} = 0.69\overline{4}$ .

When values of a RV are only *integers* (the case of most of our examples so far), we define its **probability generating function** (PGF) by

$$P(z) = \sum_{\text{All } i} z^i \cdot \Pr(X = i)$$

where z is a parameter.

Differentiating k times and substituting z = 1 yields

$$\left. \frac{d^k P(z)}{dz^k} \right|_{z=1} = \mathbb{E}[X \cdot (X-1) \cdot \dots \cdot (X-k+1)]$$

(the so called  $k^{th}$  factorial moment). For mutually *independent* RVs, we also get

$$P_{X+Y+Z}(z) = P_x(z) \cdot P_y(z) \cdot P_z(z)$$

Furthermore, given P(z), we can recover the distribution by Taylor-expanding P(z) - the coefficient of  $z^i$  is Pr(X = i).

EXAMPLES:

• For the distribution of our last example, we get  $P(z) = \sum_{i=1}^{\infty} z^i \cdot (\frac{1}{2})^i = \frac{z}{2} \cdot \frac{1}{1-\frac{z}{2}} = \frac{z}{2-z}$ (note that this can be also obtained from the MGF by  $e^t \to z$ ).

$$P'(z) = \frac{2}{(2-z)^2} \bigg|_{z=1} = 2$$
$$P''(z) = \frac{4}{(2-z)^3} \bigg|_{z=1} = 4$$

giving us the mean of 2 (check) and the variance of  $4 + 2 - 2^2 = 2$  (check).

• What is the distribution of the total number of dots when rolling 3 dice? Well, the PGF of  $X_1$ ,  $X_2$  and  $X_3$  (each) is

$$\frac{z + z^2 + z^3 + z^4 + z^5 + z^6}{6}$$

since they are *independent* RVs, the PGF of their sum is simply

$$\left(\frac{z+z^2+z^3+z^4+z^5+z^6}{6}\right)^3$$

Expanding (easy in Maple), we get:  $\frac{1}{216}z^3 + \frac{1}{72}z^4 + \frac{1}{36}z^5 + \frac{5}{108}z^6 + \frac{5}{72}z^7 + \frac{7}{72}z^8 + \frac{25}{216}z^9 + \frac{1}{8}z^{10} + \frac{1}{8}z^{11} + \frac{25}{216}z^{12} + \frac{7}{72}z^{13} + \frac{5}{72}z^{14} + \frac{5}{108}z^{15} + \frac{1}{36}z^{16} + \frac{1}{72}z^{17} + \frac{1}{216}z^{18} \blacksquare$ 

Note that a RV can have **infinite** expected value (not too common, but it can happen).

EXAMPLE: Suppose you flip a coin till the first head appears, and you win \$2 if this takes only one flip, \$4 if it takes two flips, \$8 if it takes 3 flips, etc. (the amount always doubles - i.e. you get \$2 for each of the first flips, \$4 for the third, \$8 for the fourth, etc.). What is the expected value of your win?

Clearly, you win  $Y = 2^X$  dollars.  $\mathbb{E}(Y) = 2 \cdot \frac{1}{2} + 4 \cdot \frac{1}{2^2} + 8 \cdot \frac{1}{2^3} + \dots = 1 + 1 + 1 + \dots = \infty$ .